



JetBrains MPS

Create a programming language
that the whole company can
understand

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Domain Specific Languages

- A DSL is a **focused, processable language** for describing a specific **concern** when building a system in a specific **domain**
- The **abstractions** and **notations** used are natural/suitable for the **stakeholders** who specify that particular concern.

Markus Voelter

Math

$$2 \cos z = \left(1 + \frac{\sqrt{-1}z}{\infty}\right)^{\infty} + \left(1 - \frac{\sqrt{-1}z}{\infty}\right)^{\infty} = e^{\sqrt{-1}z} + e^{-\sqrt{-1}z}$$

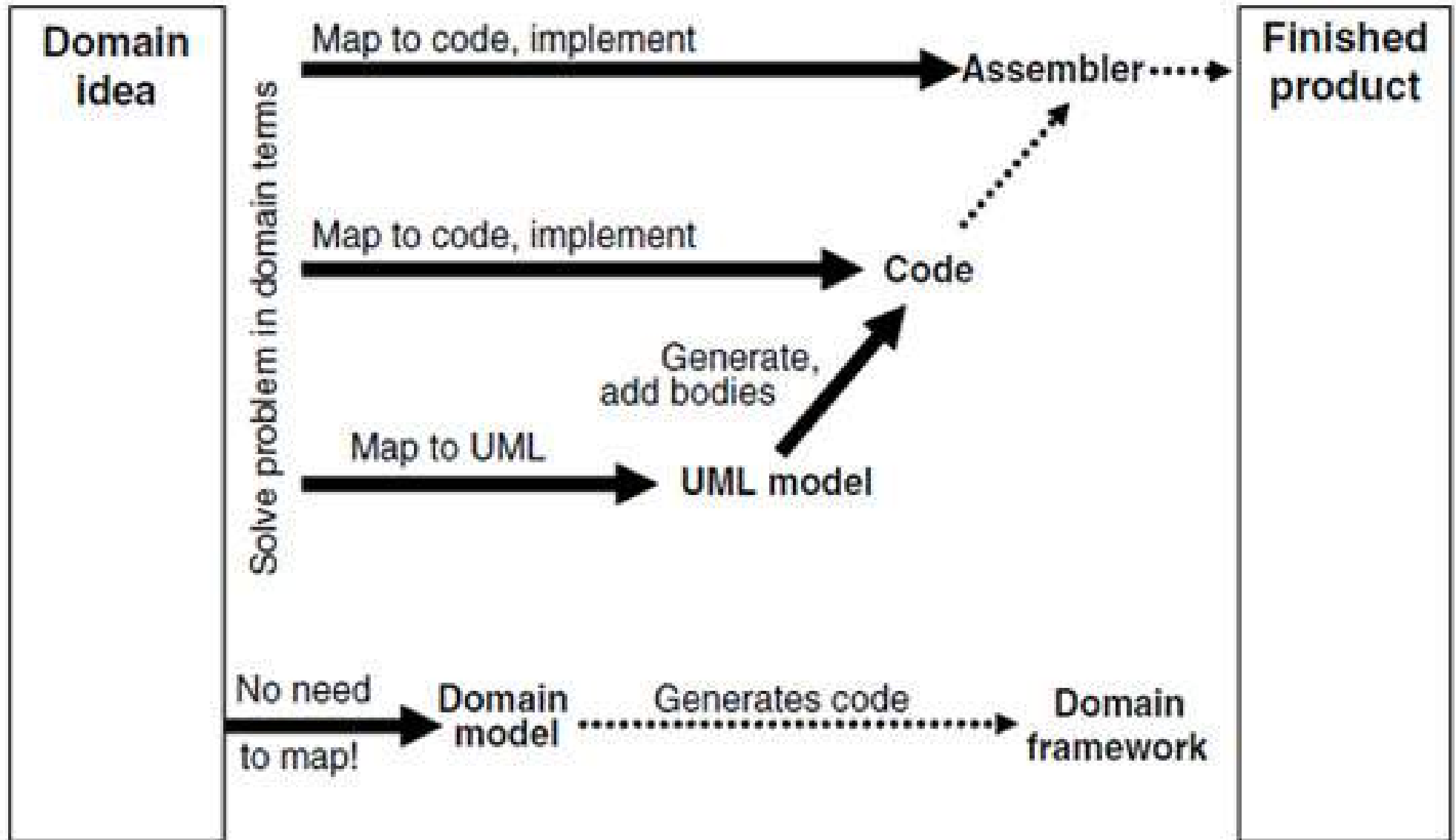
$$\Psi(x) = \sum_{k=0}^{\infty} \frac{\cos(3^k x)}{k!}$$

$$\int_{\gamma} f(z) dz = \int_a^b f(z(t)) z'(t) dt = \int_{\gamma} (u dx - v dy) + i \int_{\gamma} (v dx + u dy).$$

$$\sum_{1 \leq k \leq n} f(z(t_k))(z(t_k) - z(t_{k-1})).$$



How come?

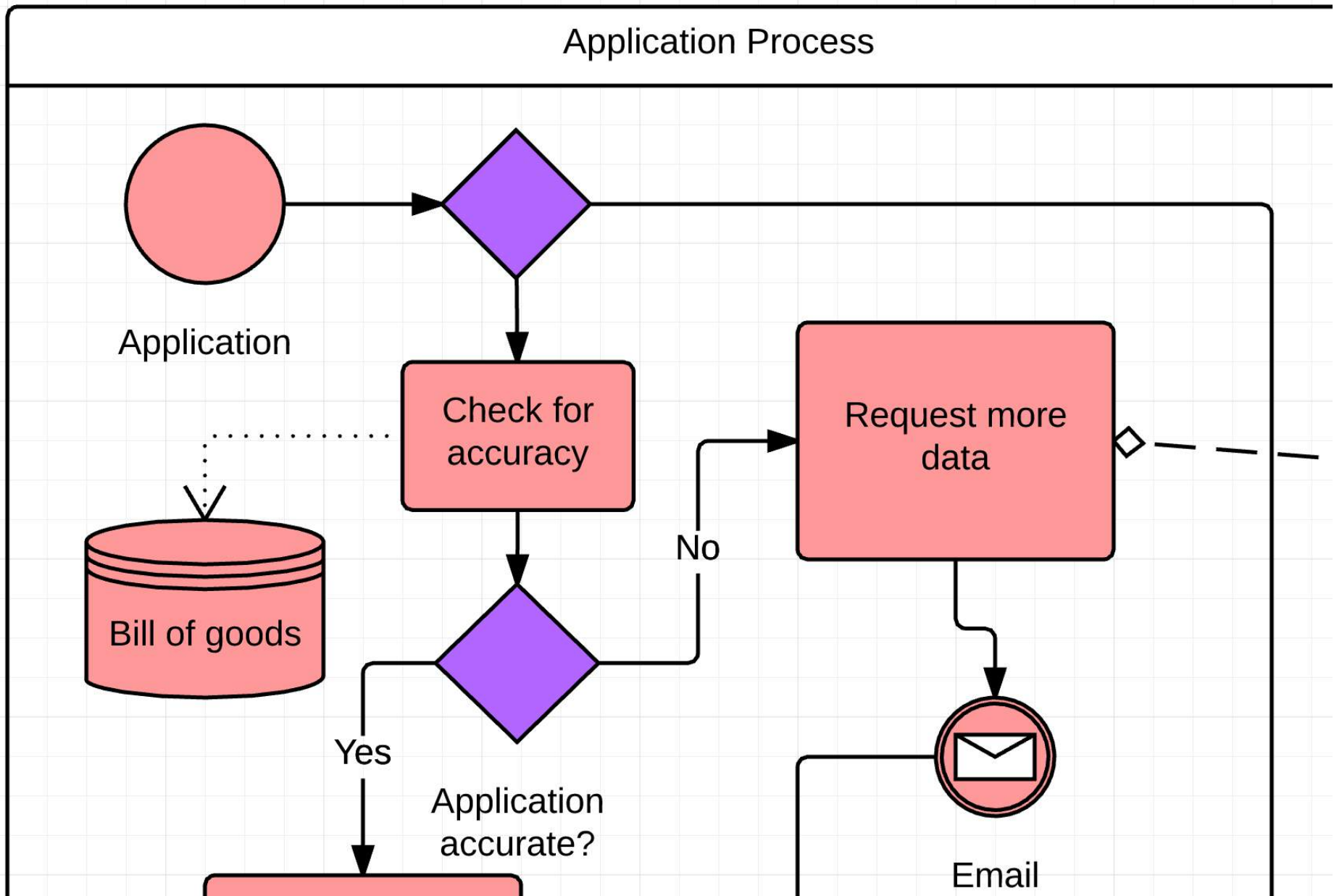


DSLs? Who cares?

You! DSLs are ubiquitous!



Buisness Processes





ма-ма | ра-ма | Шу-ра
ра-ма | ра-мы | мы-ла

Ма-ма мы-ла ра-му.

- **Health and medicine**
 - Stakeholder integration, Scalable Business, Document Generation + Certification
- **Finance**
 - Precise Specification and Implementation of Insurance Products („Rules“)
- **Government**
 - Changing Regulations, Fast Implementation, End User Empowerment
- **Automotive**
 - Code Complexity, Frameworks (Autosar), Product Lines
- **Aerospace**
 - Reduction of Accidental Complexity in Code, Process Conformance (Docs)
- **Robotics**
 - A powerful language and IDE for existing frameworks (Industry Robots, ROS)
- **Embedded software**
 - Multi-Paradigm Programming, not just Simulink and C
- **Science**
 - Consistent Derived Documents

Too narrow view of programming?



Demo

- Language to configure voice menu for an answering machine
- JetBrains MPS as a Rich Client Platform
- Business value is negligible
 - Market share of your office assistant is small



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Healthcare

Software Medical Devices Accessible to Doctors

Robustness and Correctness Required

To be FDA-certified

Needs to run on multiple target platforms

- IOS
- Android
- JavaScript



Stakeholders driving the development





Product Management
Customer Service



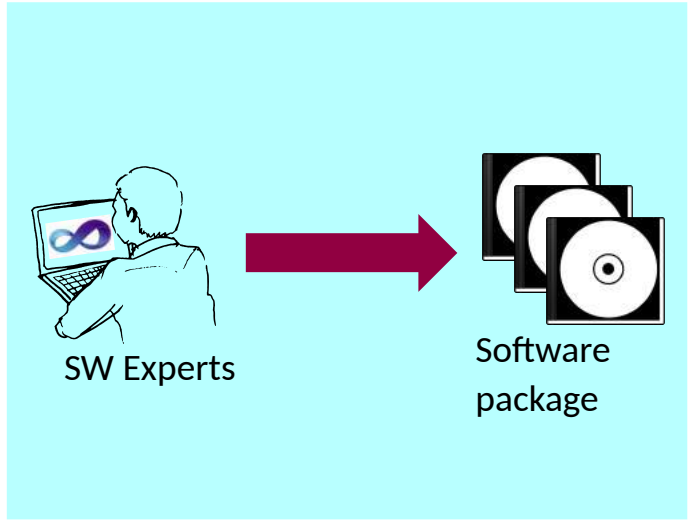
Physicists



System Engineering

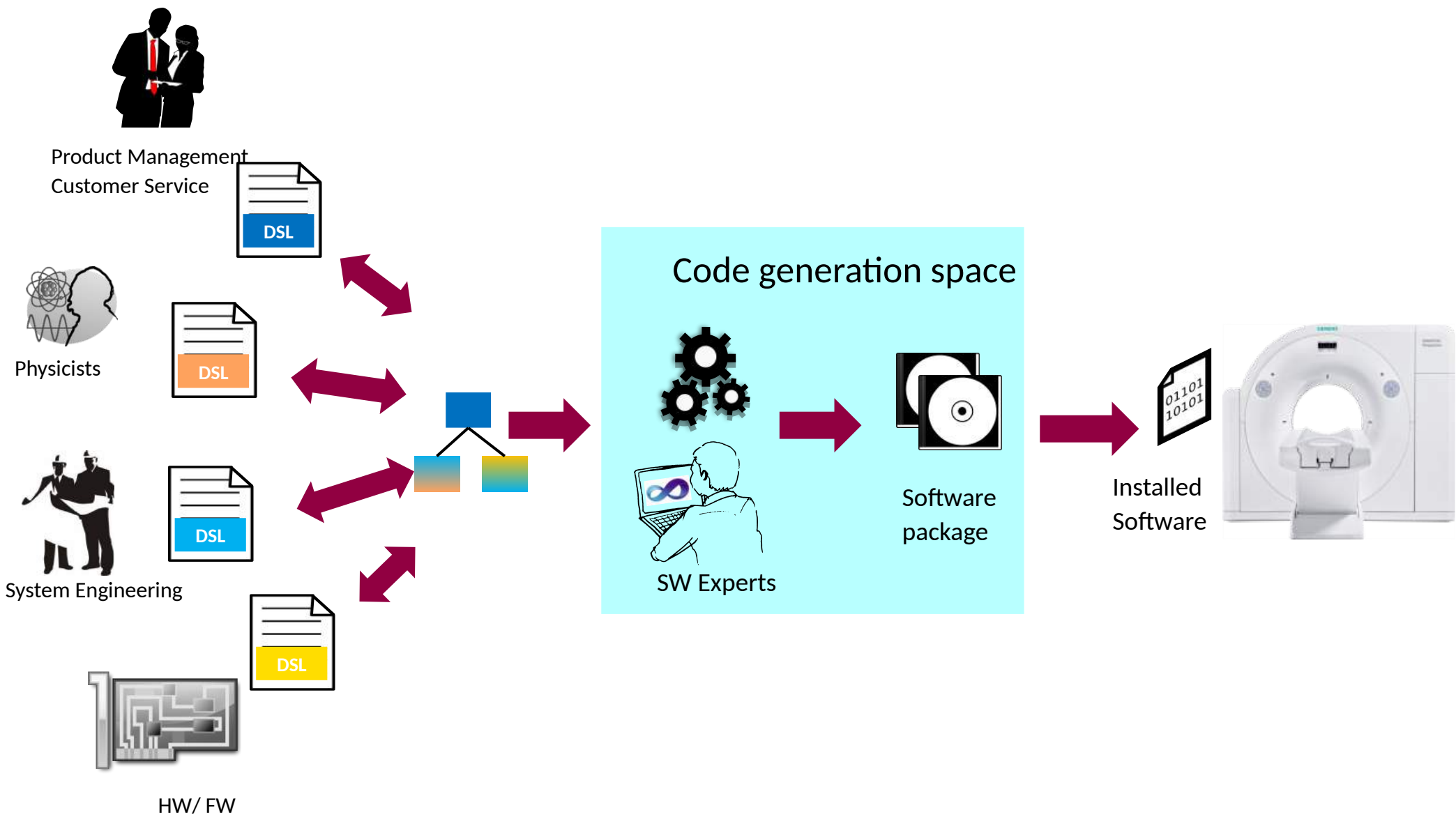


HW/ FW



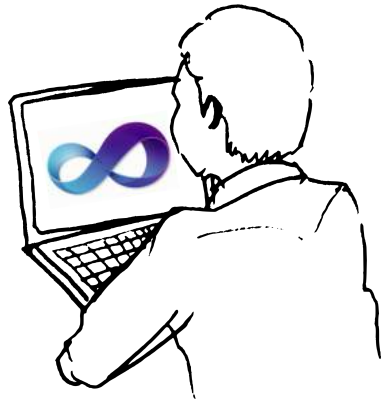
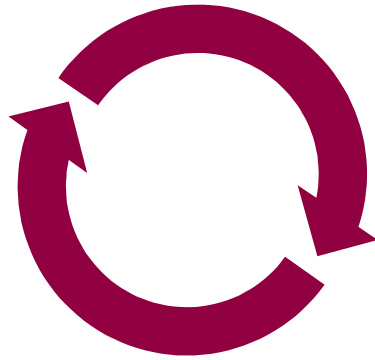
Installed
Software



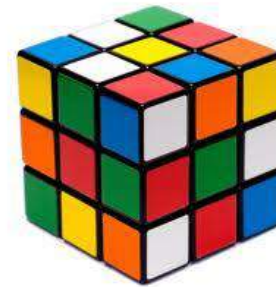




Domain Experts



SW Experts



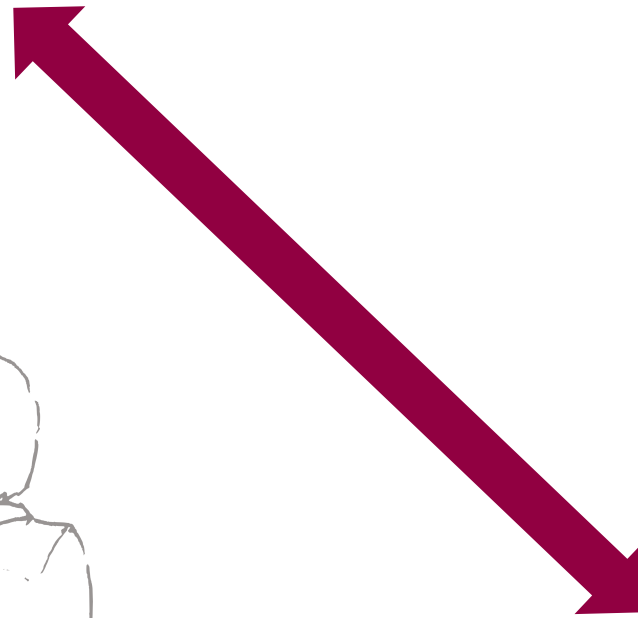
Scanner
Model / SW



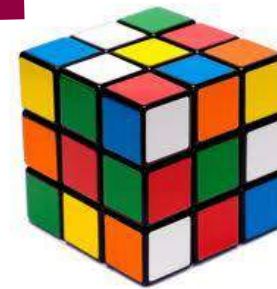
Domain Experts



SW Experts



On demand
(automatically)



Scanner
Model / SW

Focus T01

Catalogue T01_Rules imports platform_Definitions

Default clinical case: <no defaultClinicalCase>

collimation tabular rule: T01 Slot plate and coll.

description: this is a description text

	Collimation [mm]	Readout DMS [mm]	Preprocessed data matrix [mm]	Collimator Opening [mm]	Soft opening inner slot plate [mm]	Soft opening outer slot plate [mm]	Focus
(1) "30x0.1"	30x0.1	34x0.1	30x0.1	1300.000	n/a	n/a	not so big, big
(2) "30x0.1Mg"	30x0.1	34x0.1	30x0.1	1300.000	n/a	n/a	not so big, big
(3) "30x0.1AgMg"	30x0.1	34x0.1	30x0.1	1300.000	n/a	n/a	not so big, big
(4) "4x0.1"	4x0.1			n/a	1	1.1	not so big
(5) "4x0.1Mg"	4x0.1			n/a	1	1.1	not so big
(6) "3x1"	3x1	32x0.1	32x0.1	n/a	1	1.1	not so big, n/a, big
(7) "1x3"	1x3	32x0.1	32x0.1	n/a	2	2.2	not so big, big
(8) "1x3Mg"	1x3	32x0.1	32x0.1	n/a	3	3.3	not so big, big

Error: parameter must be in range

formula: Formula with Parameter References

alias: S₁

description: This is a text to describe the formula.

$$S_1 = \text{Reconstructed Slice Width} * 4 + \sum_{i=3}^{\text{Gantry rotation time}} \left(\frac{N_s}{3} \right) + (\cos(\text{Number of prepred slices}) + \text{Tube Voltage})$$

tabular rule: Tube Voltage and Filtration

description:

	Spectral Filtration	Tube Voltage [kV]
1 <	None	7, 8, 9, 10, 11, 12, 13, 14
2 <	Mg	10, 11, 12, 13, 14
3 <	AgMg	12, 14

tabular rule: Selectable wedge and filtration

description:

	Wedge Filter	Spectral Filtration	platform_Clinical_Cases
1 <	f1	None	Regular, Topogram
2 <	f1+f2	None	Case3, Case8, Case4, Case5
3 <	f1	Mg	Topogram, Case4, Case6
4 <	f1+f2	Mg	Case8, Topogram, Case4, Case6, Case5
5 <	f1	AgMg	Case9

When to DSL?

- Complex domain knowledge
- Painful translation of expertise from a domain specialist to a programmer
 - Gap in abstraction level
- Not directly related to programming
 - biology, math, insurance
 - Verification, analysis, simulation.
- Classes of applications
 - Software factories

Typical risks

- Language design takes effort
 - Adds to the cost of the project → need for reuse
- Language design skills
 - Steep learning curve
 - What goes into the language
 - How to make it elegant
- Proper tooling



MPS is an open-source language
workbench for DSL development



DSM isn't new

Xtext

{S} spoofax

 INTENTIONAL™

 MetaCase


OBJECT MANAGEMENT GROUP®



DSLs with MPS

- Abstract Syntax
- Concrete Syntax
- M2M, M2T
- Semantics: Typesystem, Dataflow
- IDE integration, UI
- Tooling: build, plugins
- Evolution/migration
- Deployment: custom IDE, RCP

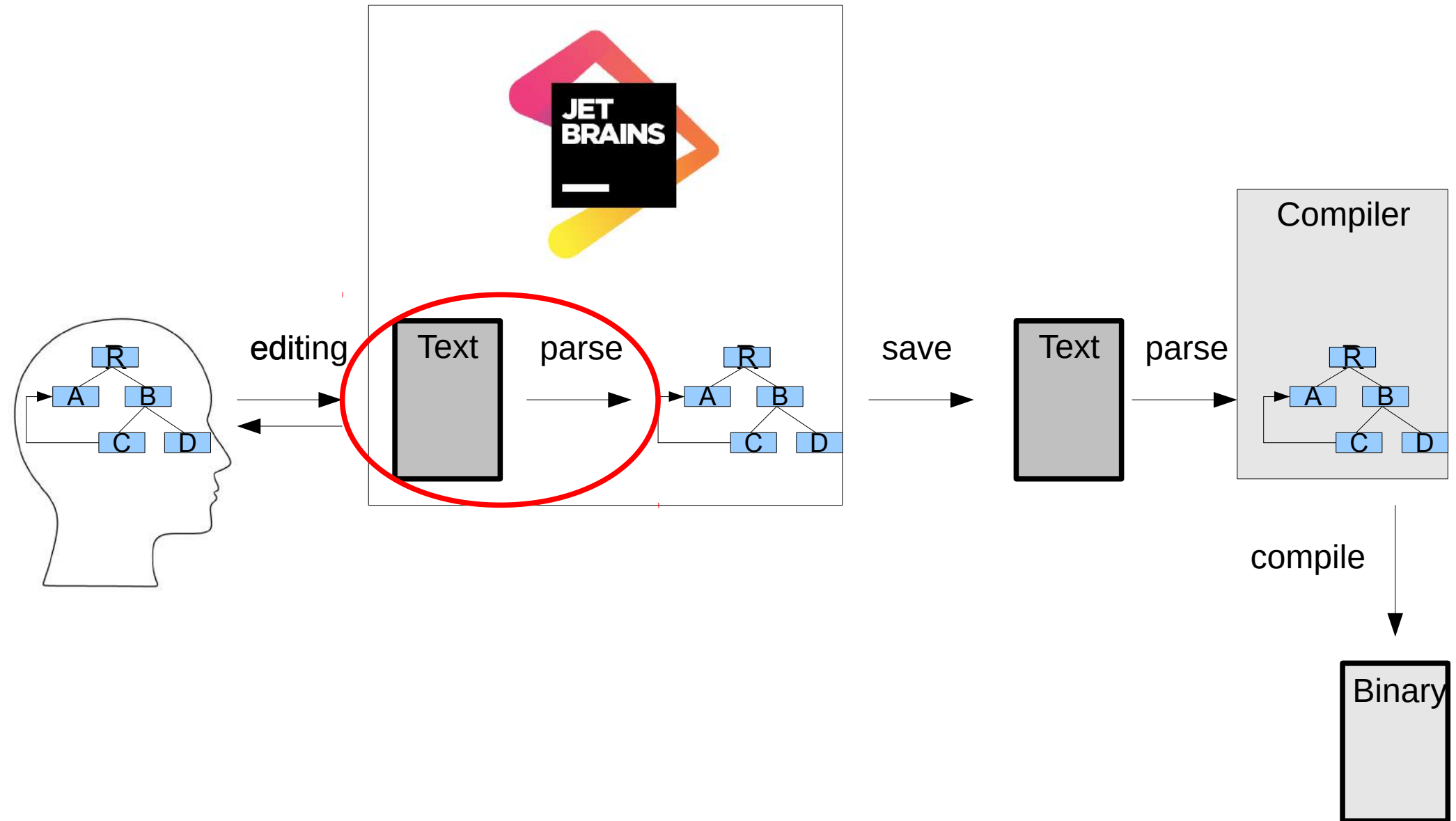


DSLs with MPS

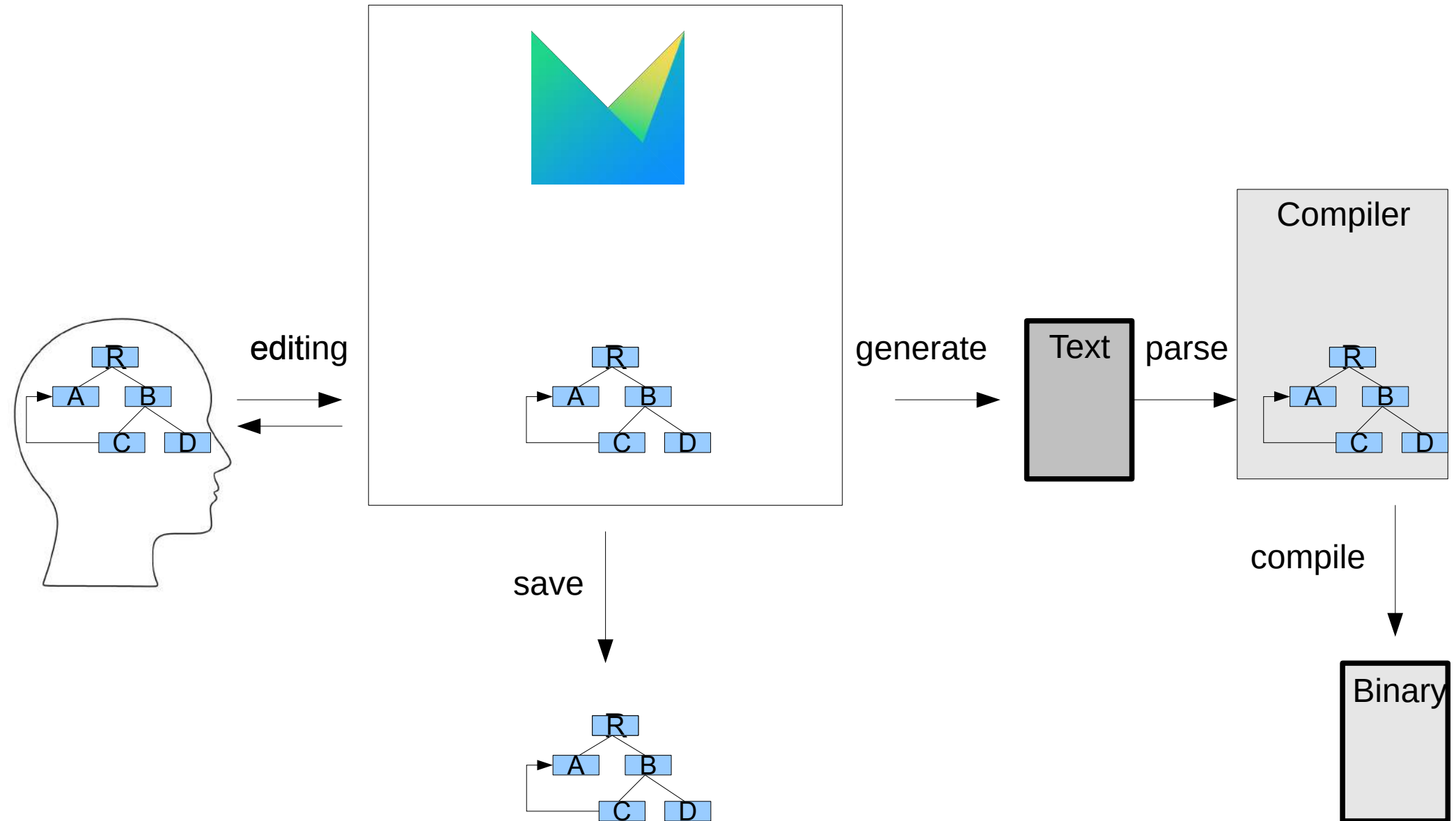
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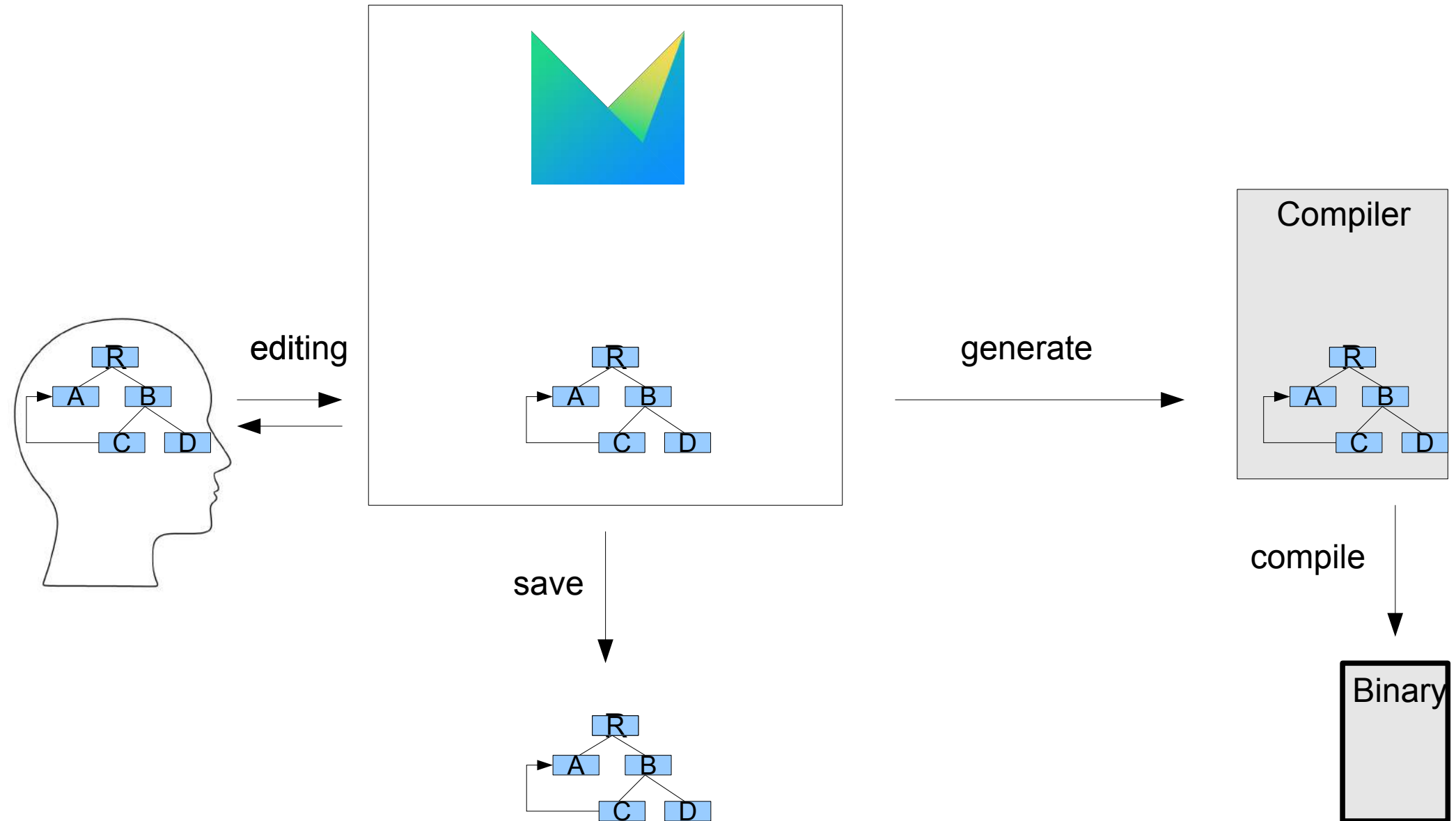
Textual editing



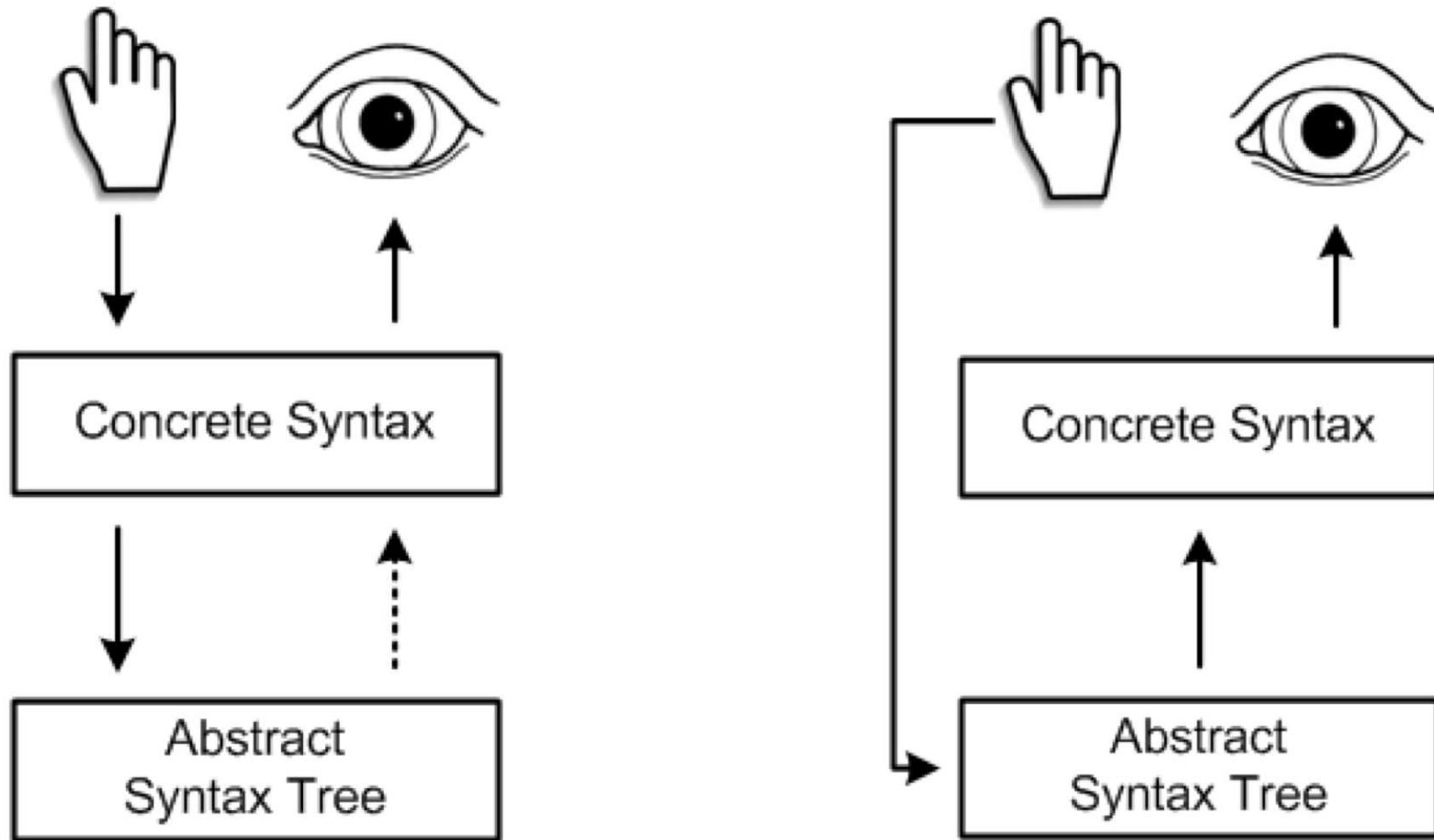
Projectional editing



Projectional editing



Projectional editing



Rich syntaxes

```
public class Gol {
    public static void main(String[] args) {
        new Gol().run();
    }
    public void run() {
        sequence<Coordinate> generation = new arraylist<Coordinate>{(4, 5), (5, 5), (6, 5)};
        for (int i = 0; i < 5; i++) {
            System.out.println("Next generation: " + generation);
            generation = nextGeneration(generation);
        }
    }
    private sequence<Coordinate> nextGeneration(sequence<Coordinate> generation) {
        set<Coordinate> candidates = new hashset<Coordinate>;
        candidates.addAll(generation);
        generation.forEach({~it => candidates.addAll(neighbors(it)); });
        set<Coordinate> nextGeneration = new hashset<Coordinate>;
        foreach c in candidates {
            if (boolean Default: dead


|                                         | generation.contains(c) | !generation.contains(c) |
|-----------------------------------------|------------------------|-------------------------|
| countAliveNeighbors(generation, c) < 2  | dead                   | dead                    |
| countAliveNeighbors(generation, c) == 2 | alive                  | dead                    |
| countAliveNeighbors(generation, c) == 3 | alive                  | alive                   |
| countAliveNeighbors(generation, c) > 3  | dead                   | dead                    |


) {
                nextGeneration.add(c);
            }
        }
        return nextGeneration;
    }
    private sequence<Coordinate> neighbors(Coordinate cell) {
        ((cell + [


|        | left     | middle  | right   |
|--------|----------|---------|---------|
| upper  | (-1, 1)  | (0, 1)  | (1, 1)  |
| middle | (-1, 0)  | (0, 0)  | (1, 0)  |
| lower  | (-1, -1) | (0, -1) | (1, -1) |


]) - cell).asSequence;
    }
    private int countAliveNeighbors(sequence<Coordinate> currentGeneration, Coordinate cell) {
        return neighbors(cell).intersect(currentGeneration).size;
    }
}
```


Tabular notations

[checked]

exported statemachine FlightAnalyzer initial = beforeFlight {

States	Events	
	next(Trackpoint* tp)	reset()
beforeFlight	[tp->alt > 0 m] -> airborne	
airborne	[tp->alt == 0 m && tp->speed == 0 mps] -> crashed [tp->alt == 0 m && tp->speed > 0 mps] -> landing [tp->speed > 200 mps && tp->alt == 0 m] -> airborne { points += VERY_HIGH_SPEED; } [tp->speed > 100 mps && tp->speed <= 200 mps && tp->alt == 0 m] -> airborne { points += HIGH_SP	[] -> beforeFlight
landing	[tp->speed == 0 mps] [tp->speed > 0 mps] - { points--; }	
landed		
crashed		

Core Data DefaultRegions for entity BillingRegion

Code	Name	Base Min Price	Max Rebate Factor
BW	Baden Württemberg	0.20	0.8
BY	Bayern	0.20	0.8
BE	Berlin	0.15	0.7
BB	Brandenburg	0.10	0.7
HB	Bremen	0.20	0.7
HH	Hamburg	0.15	0.7
HE	Hessen	0.15	0.7
MV	Mecklenburg-Vorpommern	0.10	0.7
NI	Niedersachsen	0.15	0.7
NW	Nordrhein-Westfalen	0.15	0.7
RP	Rheinland-Pfalz	0.15	0.7
SL	Saarland	0.15	0.7
SN	Sachsen	0.10	0.7
ST	Sachsen-Anhalt	0.10	0.7
SH	Schleswig-Holstein	0.15	0.7
TH	Thüringen	0.10	0.7

Symbolic notations

```
int32 sumUpIntArray(int32[] arr, int32 size) {  
    return  $\sum_{i=0}^{\text{size}} \text{arr}[i]$ ;  
} sumUpIntArray (function)
```

```
int32 averageIntArray(int32[] arr, int32 size) {  
    return  $\frac{\sum_{i=0}^{\text{size}} \text{arr}[i]}{\text{size}}$ ;  
} averageIntArray (function)
```

```
double midnight1(int32 a, int32 b, int32 c) {  
    return  $\frac{-b + \sqrt{b^2 - 4 * a * c}}{2 * a}$ ;  
} midnight1 (function)
```

```
double midnight2(int32 a, int32 b, int32 c) {  
    return  $\frac{-b + \sqrt{b^2 - \sum_{i=1}^4 a * c}}{2 * a}$ ;  
} midnight2 (function)
```

```
double sumOfProductsOfLogs(int32[] arr, int32 size) {  
    return  $\sum_{k=0}^{\text{size}} \frac{\prod_{i=0}^k \log_2 \text{arr}[i]}{2}$ ;  
} sumOfProductsOfLogs (function)
```

Positional notations

Rule Set Type DemoRuleSetType

Business objects

person : Person

Variables:

PRMI : int

FR : int

NN : int

TT : int

J : int

A3 : int

G3 : int

ANUI : int

X : int

Parent

<no parent>

Libraries

Standard

Extra

Rule Set Type DemoRuleSetType

Business objects

<no business objects>

Variables:

<no variables>

Parent

<no parent>

Libraries

<no libraries>

Multiple switchable notations

```

}
component kernel subsystem <<module>> {
  input ports:
    << ... >>
  output ports:
    smodel
    openapi
    Tuples-runtime
    Closures-runtime
    collections-runtime
    typesystemEngine
  dependencies:
    depends on smodel
    depends on Tuples-runtime
    depends on collections-runtime
    depends on typesystemEngine
}
component typesystemEngine subsystem <<
input ports:

```

	openapi	Tuples-runtime	Closures-runtime	smodel	collections-runtime
openapi					
Tuples-runtime					
Closures-runtime					
smodel	+				
collections-runtime			+		
kernel		+		+	+
typesystemEngine					+

Combine languages

variables:

```

int x1           = 10 * (1 + 2)           ==> 30
int x2           = 20                    ==> 20
boolean b1       = true || !false        ==> true
int b2           = if [ b1 then 12 else 13 ] ==> 12
list<int> intList = list(1, 2, 3)         ==> [1, 2, 3]
int three        = intList.last           ==> 3
list<int> t2      = intList.where|it > 2|  ==> [3]
boolean allEl    = intList.all|it > 0|    ==> true
int surprise2    = doWithTwoInts(:add, 1, 3) ==> 4
[int, int] tuple = [1, 2]                ==> [1, 2]
int one          = tuple[0]               ==> 1
int c1           = alt [ x1 < 0 && x2 > 1 => 2 ]
                  [ x1 > 0 && x2 == 1 => 1 ] ==> 0
int c2           =                       ==> 9

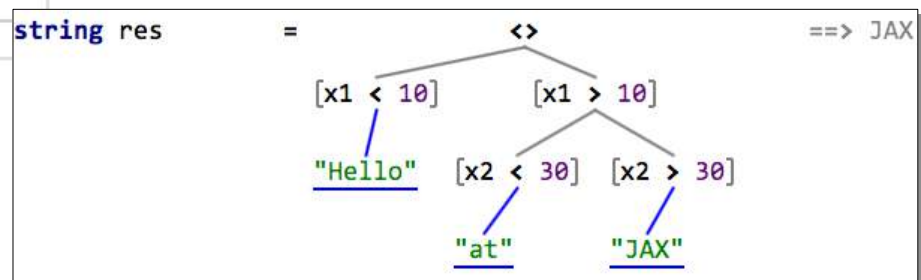
```

	x1 < 0	x1 == 0	x1 > 0
x2 < 0	1	2	3
x2 == 0	4	5	6
x2 > 0	7	8	9

```

int complicated = {
  val t1 = 10 + 20
  val t2 = t1 + 30
  t2
}

```



functions:

```

fun add(int a, int b) : int = a + b
fun doWithTwoInts((int, int => int) fun, int a, int b) : int = fun.exec(a, b)
fun anotherFun(option<int> i) : int = with some i as x => x + 1 none 20
fun giveMeAnInt() : int = anotherFun(some(10))
fun getStreets(Person p) : collection<string> = p.workedAt.offices.street

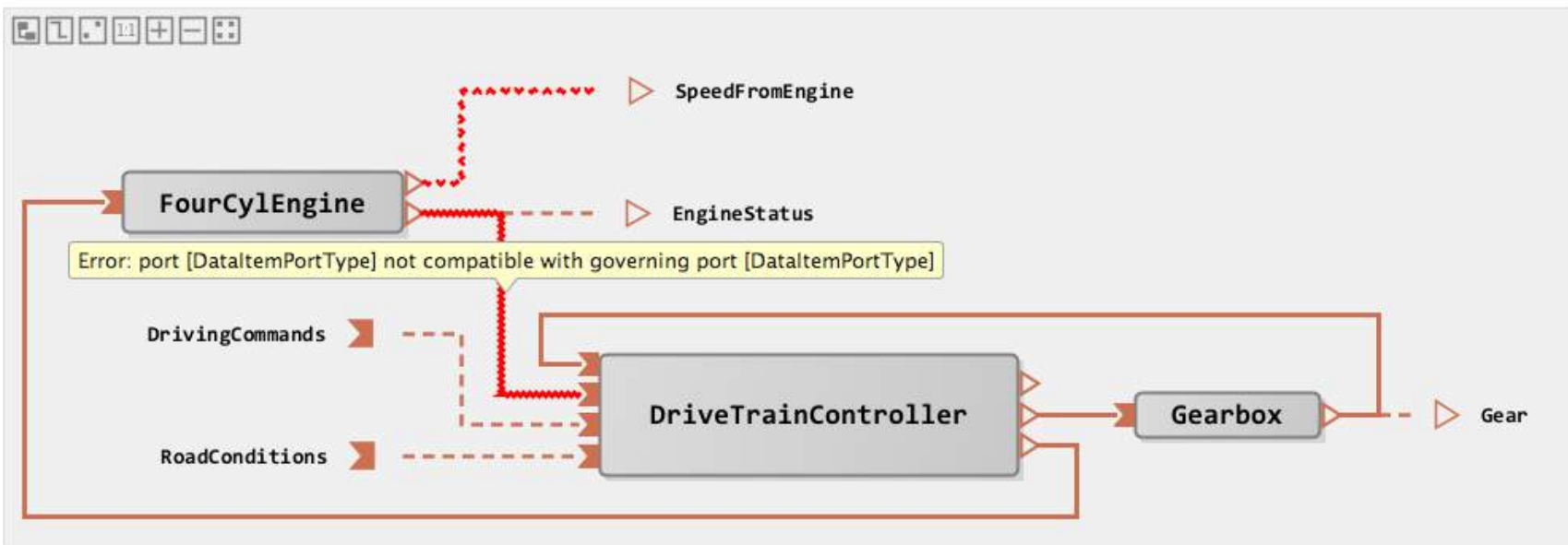
```



```

public functional component DriveTrain {
  produces SpeedFromEngine
  produces EngineStatus
  produces Gear where it < gearsCount
  consumes RoadConditions
  param int gearsCount
  consumes DrivingCommands
}

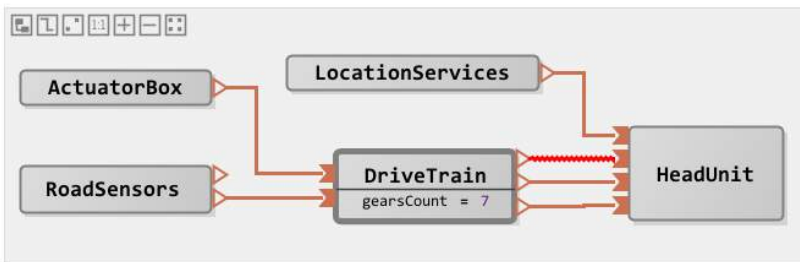
```



```

}
functional component Car {

```



```

}

```

Parsing is the bottleneck

... of language expressiveness

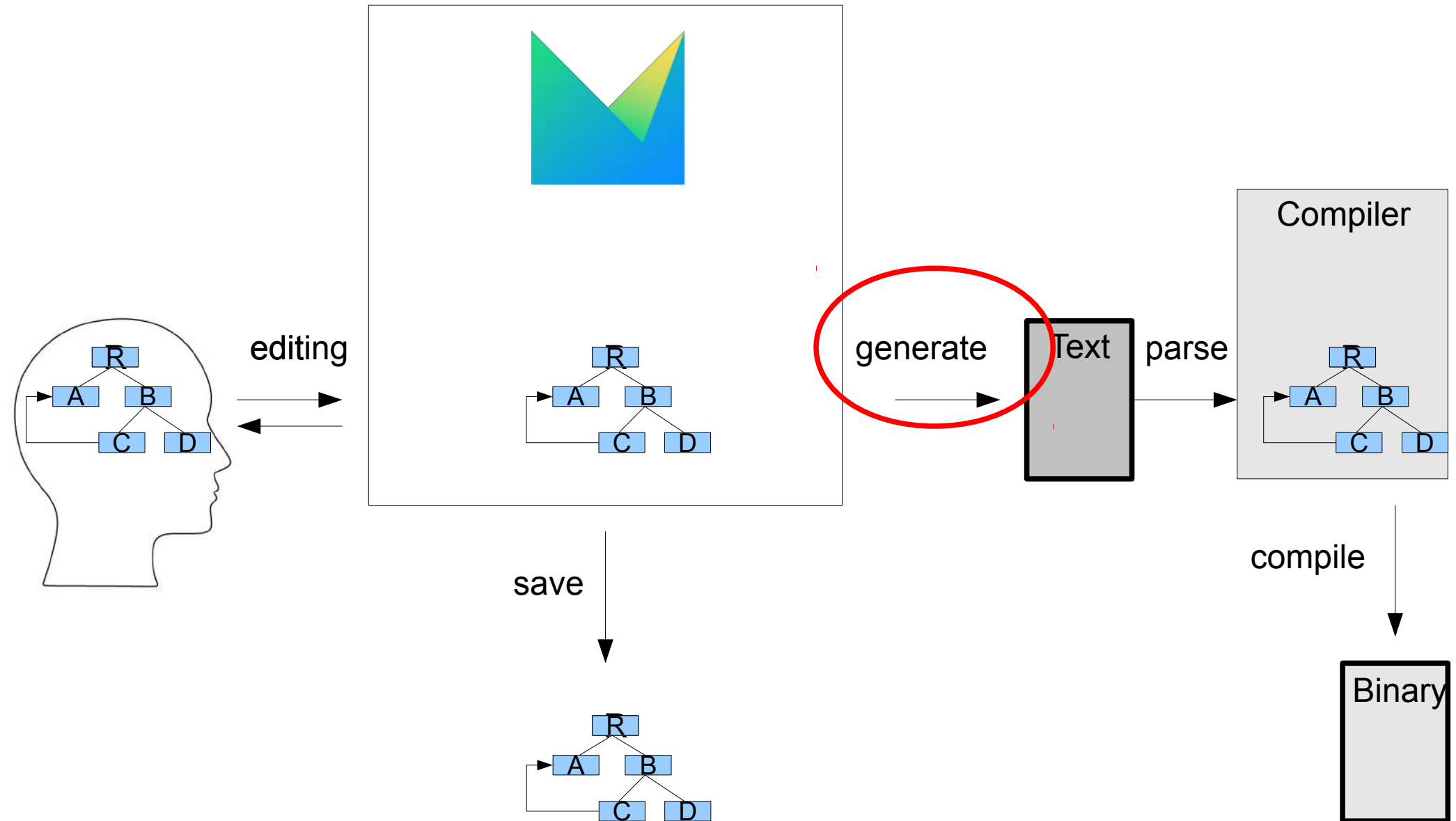
- Limits the **possible** syntaxes
- Allows only **one** editable code visualization
- Complicates **combining** languages

DSLs with MPS

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- Concrete Syntax
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Code generation

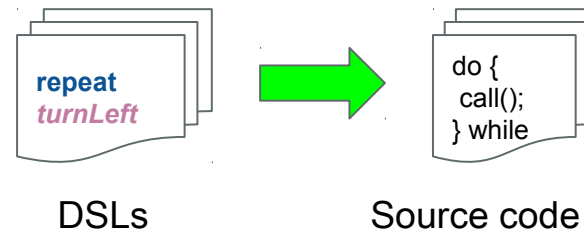
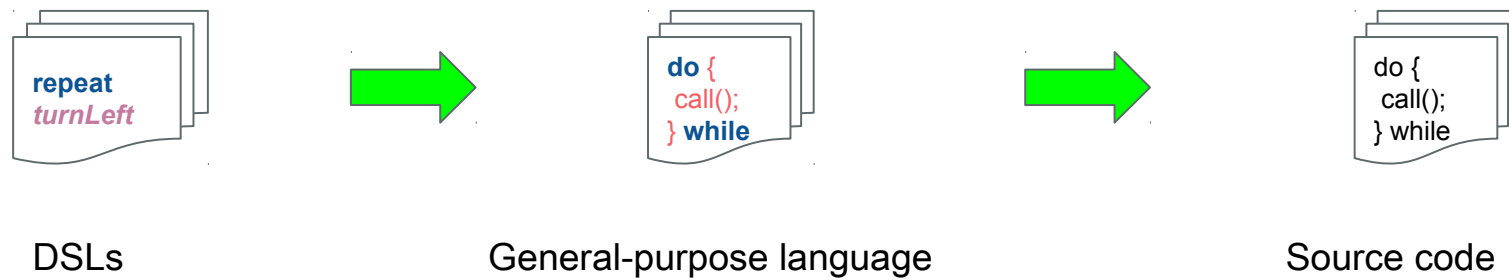


Generators

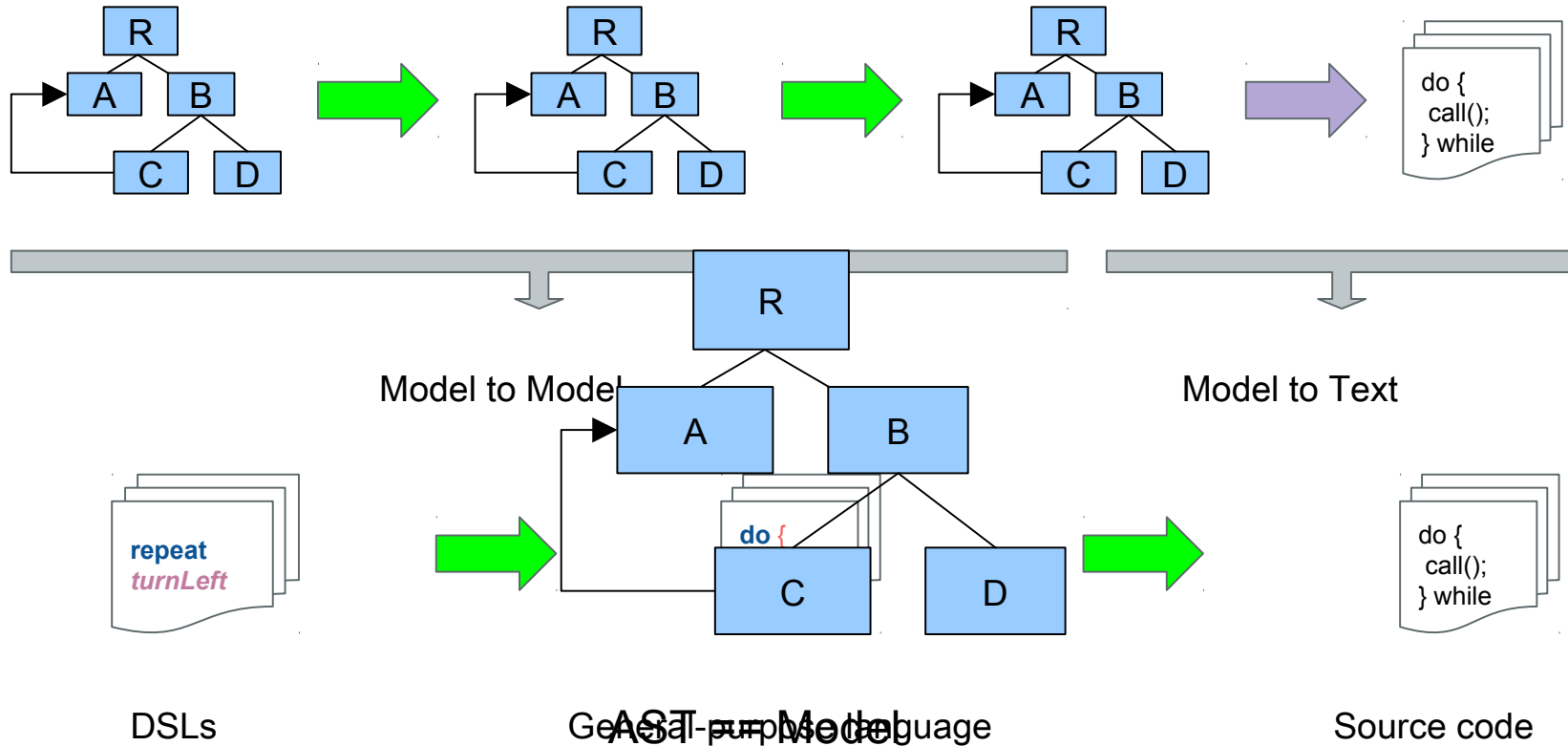
Map solutions from a **problem domain** to an **implementation domain**

- Transform models
- Output **models** or **text**

Compiler analogy



OMG/MOF Perspective



SIEMENS



Mercedes-Benz

 UNIVERSITY OF AGDER

 **OHB**

fortiss



BOSCH



HUAWEI

Continental 

 **Whirlpool**
CORPORATION



McGill

UNIVERSITY OF
WATERLOO

DYNAGEN[®]
power controls you can trust

SIoux 



Belastingdienst

itemis

i2S
INSURANCE KNOWLEDGE





jetbrains.com/mps

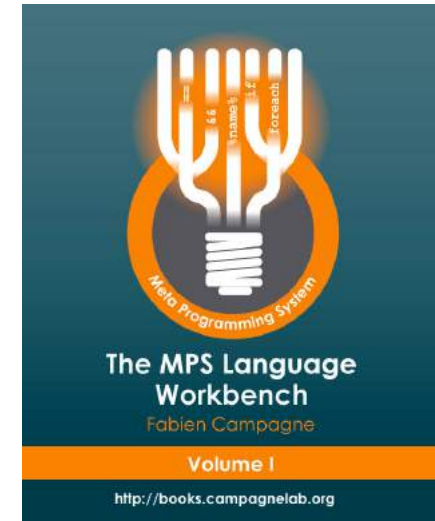
Thank you
for your attention

—

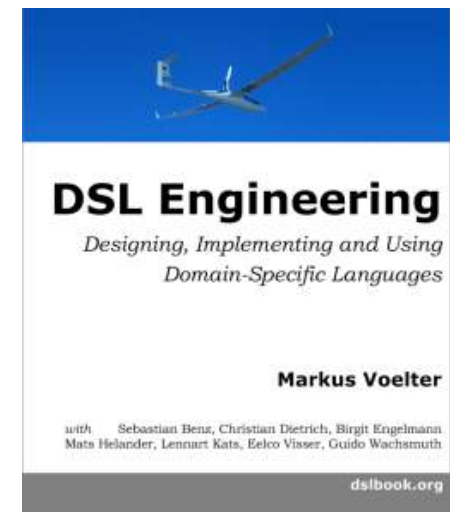


Books

- <http://books.campagnelab.org>



- <http://dslbook.org>



<https://www.jetbrains.com/mps/publications>